



# Human Exoskeleton

## Team J

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*Khaled Alzafairi - 04.24.2017 - Lerner-Exoskeleton-Mount*

# Project Description

- The project is about designing an Adjustable Human-Exoskeleton Mounting Interface.

## ➤ Client's Information :

Zach Lerner, Ph.D.  
Director of NAU'S Biomechatronics Lab.

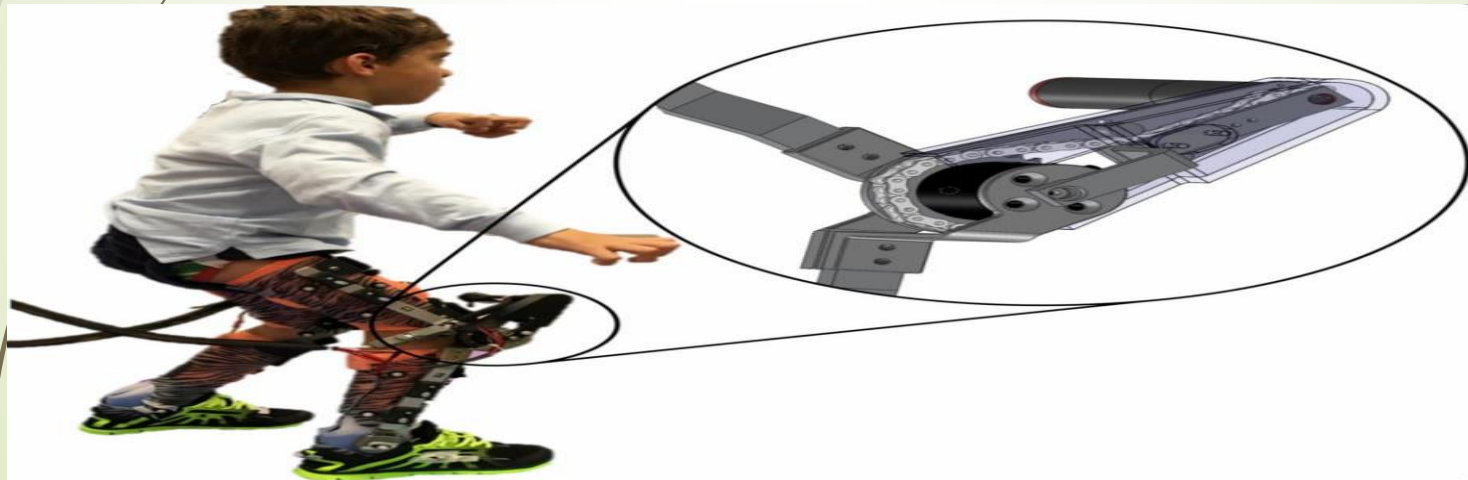


Figure 1 : Human Exoskeleton Mounting Interface.

# Design Description

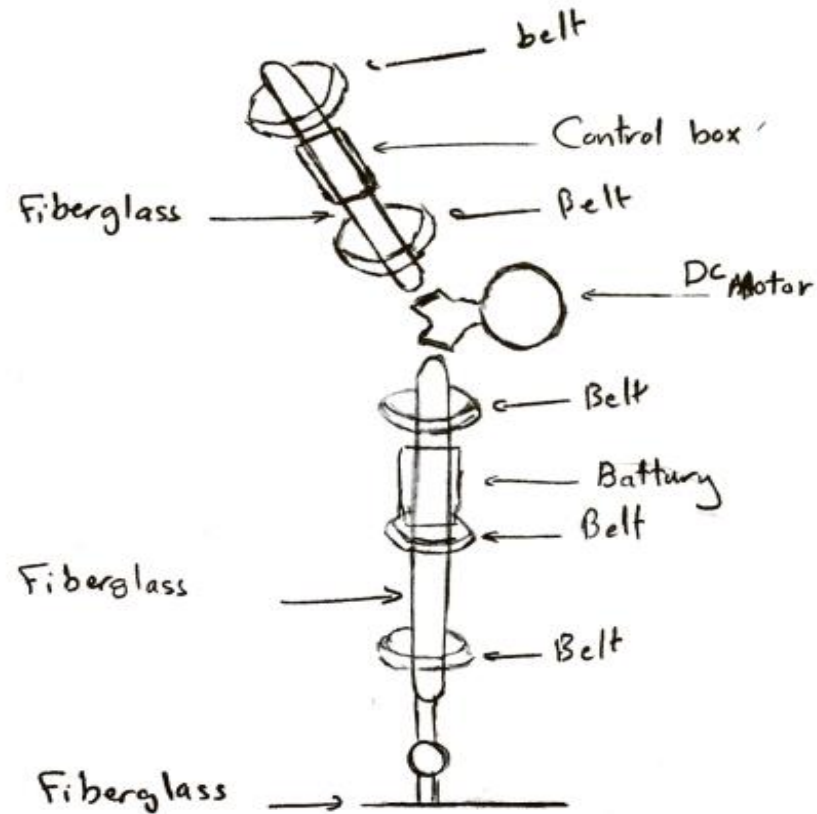


Figure 2 : Final Design

# Design Function

- Belts
- Motor
- Fiber Glass
- EE System :  
Control Box  
Sensor  
Battery

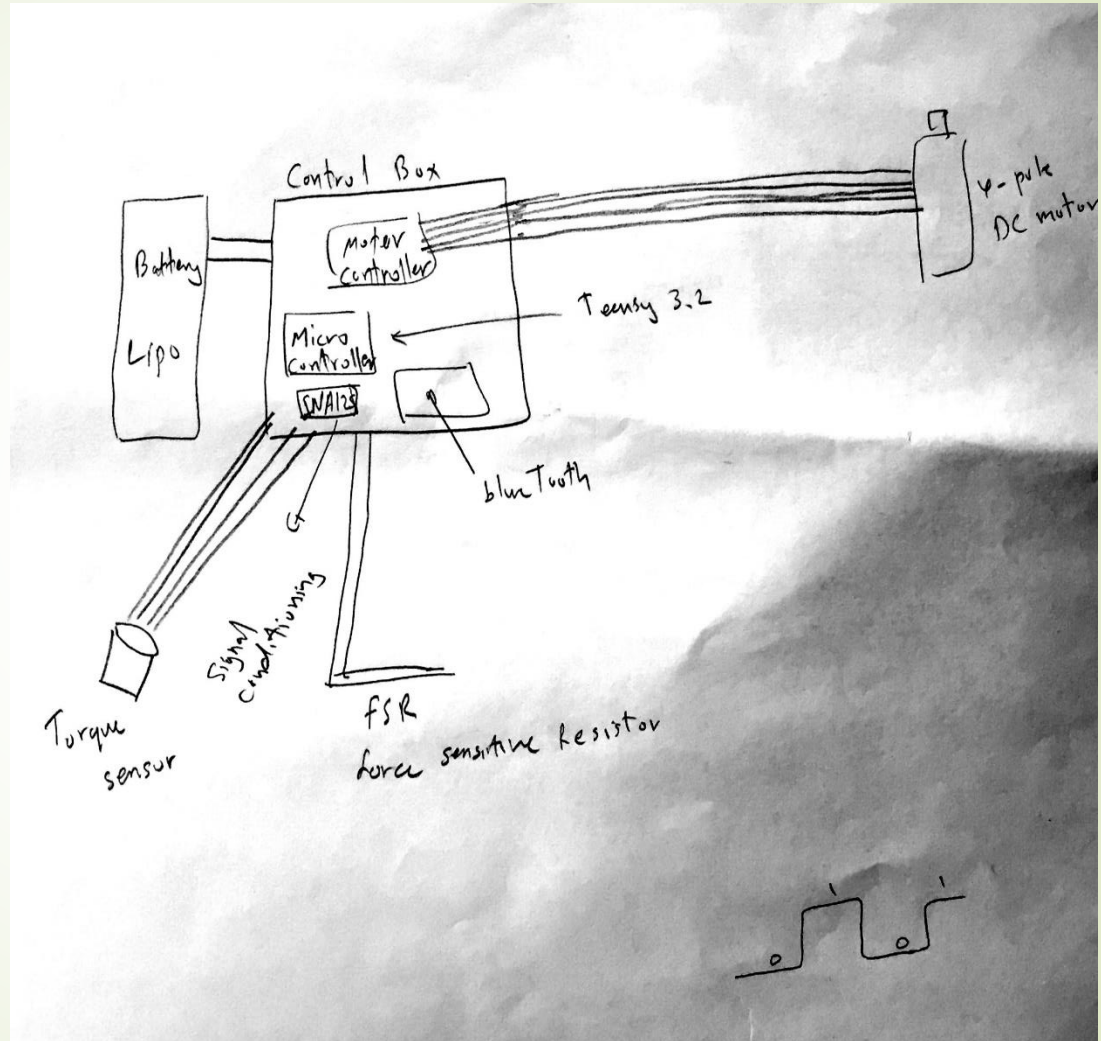


Figure 3 : Control Box

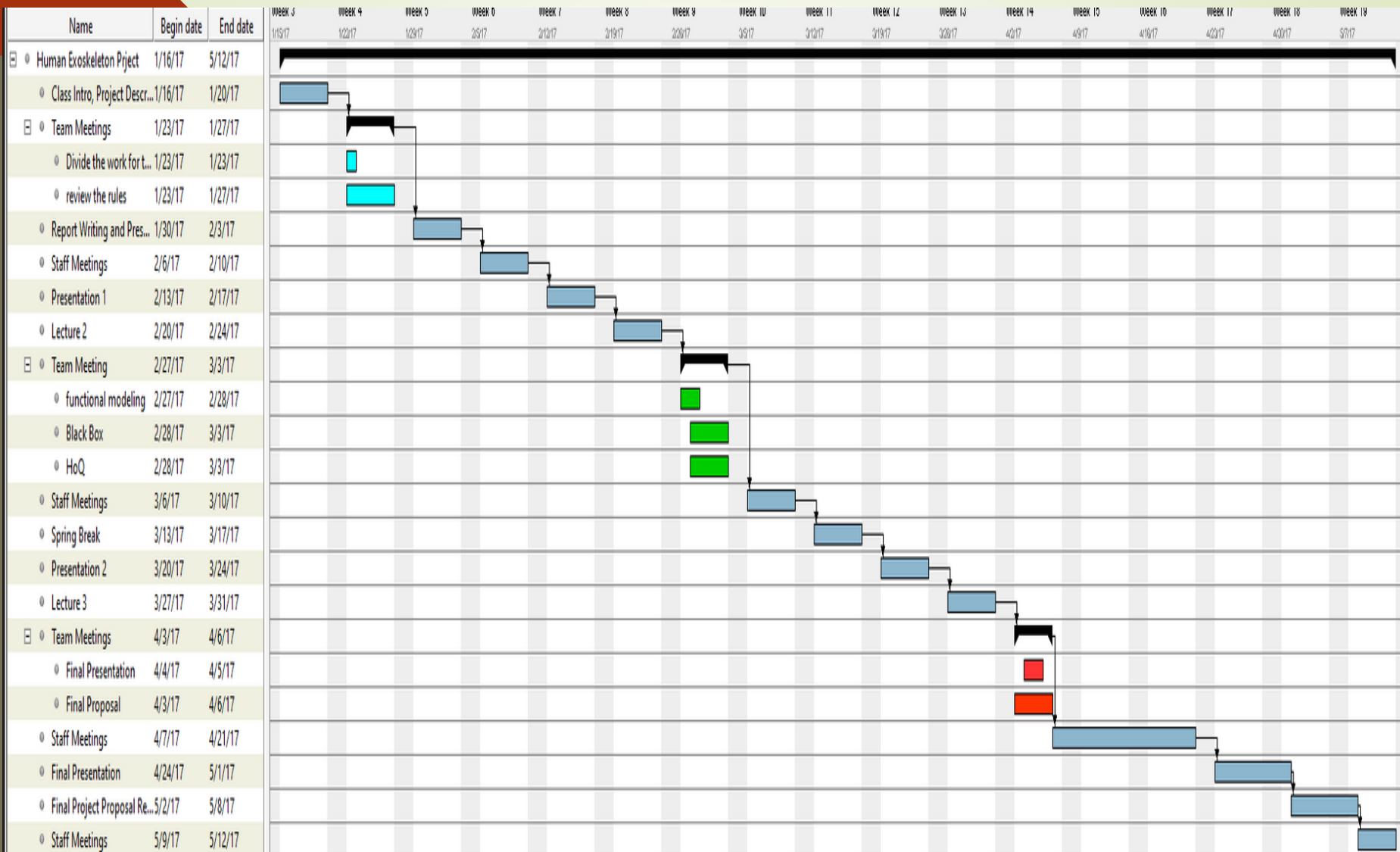
# Design Requirements

- Light in weight
- Adjustable
- Provide rigid mounting points to the thigh, shank and foot
- Low Profile
- Minimize skin irritation

# House of Quality

<b>Customer Requirement</b>	<b>Weight</b>	<b>Engineering Requirement</b>	<b>Yield strength of at least 40 N/m<sup>2</sup></b>	<b>Adjustable to a length ranging 6 to 20</b>	<b>Time to don/doff 30 sec-5 min</b>	<b>Limited weight of 0.75 kg/limb</b>	<b>No dimensions beyond the knee of 5cm</b>
Should be adjustable	4			5			4
Have good mounting grip	5		4				
Easy to wear and remove	4				5	3	4
Reduce the irritation caused by the fabric	4						4
Compatibility with shoes and clothing	3			3	4		
Strong and lightweight	5		5			5	5
<b>Absolute Technical Importance (ATI)</b>							
<b>The Relative Technical Importance (RTI)</b>							
<b>Target(s)</b>							
<b>Tolerance(s)</b>							
<b>The Testing Procedure (TP#)</b>							

# Schedule & Budget



# Budget (\$500+Electric System)

- Estimated Cost :

- 1- Materials (40%)
- 2- Advertisement (20%)
- 3- Manufacturing (30%)
- 4- Prototyping (10%)

- Electric System :

- 1- FSR (\$20.95)
- 2- Micro-controller (\$22.80)
- 3- Blue-tooth (\$24.95)
- 4- Torque Sensors (\$675.00)
- 5- Li-Po Battery (\$62.99)





Questions ?